

Lexium Motion Module Developer's Kit LMM-KIT2

In the box

The Lexium Motion Module Developer's Kit contains everything necessary to begin developing LMM applications. Items included are

- Lexium Motion Module
- 1-axis Development Board
- USB to CANopen Converter
- NEMA 17 (42mm) motor + encoder
- 24 VDC Power Supply

LMM Developer's Kit

PCB module, development board and motor

Prerequisites

In addition to the included components, setup also requires a PC running Windows 7 or greater.

Starting up

- Connect the components shown in Figure 1. The individual components come pre-wired for ease of setup.
- 2. Connect the enable input. The "Enable" input must be at a level in relation to the Input Reference that results in current flow. See Figure 2 for interface options.

NOTE: The default, disconnected state of the enable input is "disabled." Motion will not occur if this input is left floating and an error 14 will assert.

- Download and Install and open Lexium Software Suite from the SEM website at http://motion.schneider-electric.com.
- 4. From the Software Suite Launch dialog, install the CANopen Interface



NEMA 17 (42mm) motor + encoder

Figure 1: Connect LMM Developer's Kit components

Enable input

always enabled, sinking



Enable input

switched enable, sourcing



Figure 2: Connect the enable input

Resources



http://j.mp/int-Imm1 Interface Board Schematic

Initialize communication

- With DC power and CAN bus connected, apply power to the Lexium MDrive.
- Open the CANopen Configuration Utility
- Click the button «CAN Init»
 - The USB to CANopen Bus container will display the connection status as shown at right. Additionally the LED on the MD-CC501-000 should be blinking rapidly.

Change Node ID/BAUD rate

The defaults for the Lexium MDrive are:

- Node ID: 41 hex
- BAUD rate: 1 Mbps

NOTE: when changing the Node ID, the change takes place instantaneously, changing the BAUD rate requires a power cycle of the Lexium MDrive when using the CANopen Configuration Utility.

To change the settings

- Change the default Node ID to the desired ID
- Change the BAUD rate to the desired setting
- Click the «Set Nofe Id» button
- Click the «CAN Close» button to close the connection to the CAN bus.
 - \lhd Cycle power to the Lexium MDrive
- Click the «Find Node Id» button
 - The Lexium MDrive will be reconnected at the new Node ID/ BAUD rate

Perform functional testing

Toggle the state machine

Click Toggle Operation Mode to cycle through the state machine. You are ready to perform functional testing when the Status word field reads 0637h - Operation Enabled

Move the motor

- Select the DSP402 motion profile.
- Enter a value the field (by default 51200 steps, or one revolution is entered).
- Click «Go»
- \lhd The motor will move, verifying functionality
- NOTE: If profile velocity was selected the motor will accelerate to the entered velocity. Motion my be halted by clicking «Motion» and resumed again by clicking «Halt».

| USB to CANopen Bus | |
|---|--------------------------------------|
| CAN Init | Initted, 0, 1M |
| CAN Status | 0h = ok |
| CAN Close | |
| | |
| | |
| Info | |
| USB-CAN Hardware Info | |
| ID = 741h, Data ID = C1h, Data ID = C1h, Data | a = 0 = 20811100000 = 00000000 |

| Settings | | |
|---------------------|---------------|--|
| Node ID | Baud | |
| 41 Hex | 0 = 1 Mbits 🔔 | |
| Set Node Id | | |
| Find Node Id | | |
| Cycling Nodeld: 41h | | |

Commande and Perinherals

| Commanda and r enprioraia | | |
|--|--|--|
| Toggle Operation Mode | | |
| Status Word 0660h = Switch On Disabled | | |
| Profile Position | | |
| 31200 | | |
| Go Motion | | |
| 4 3 2 1 Input I/O ■ ■ ■ Output I/O ♥ ■ ♥ | | |



Intelligent motion systems

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